

Optimal Control in a Smart Grid Aggregator

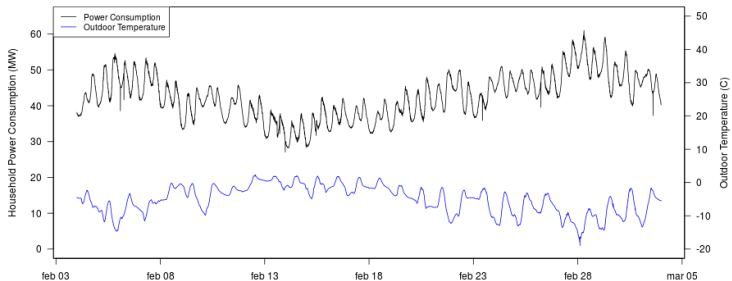
Jonathan Ridenour, Joachim Lindborg

October 15, 2018

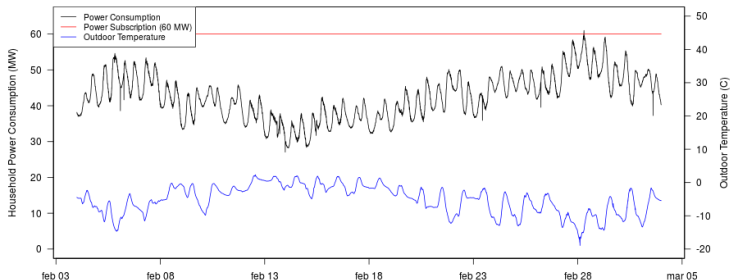
Overview

- 1 Critical peak power, what do we mean?
- 2 Critical peak power: a problem for DSOs.
- 3 Coordinating Power Control: VäxEl.
- 4 Model Predictive Control.
- 5 Björklinge, Uppland.
- 6 Simulation results.

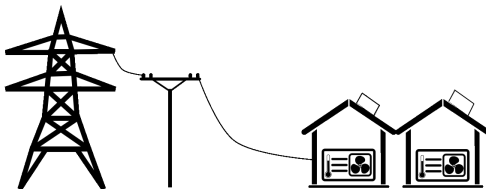
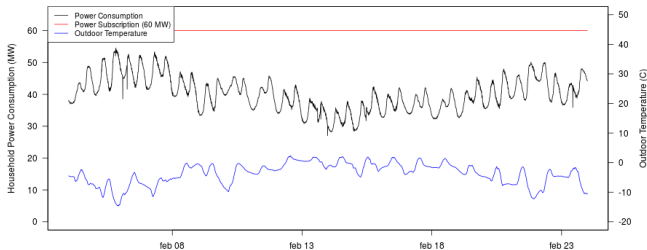
Critical peak power, what do we mean?



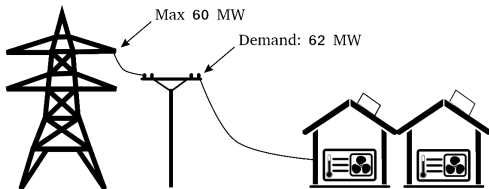
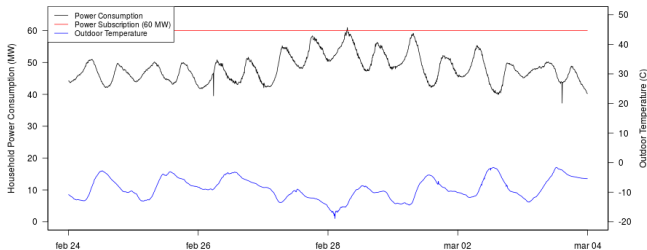
Critical peak power may only occur once or twice a year.



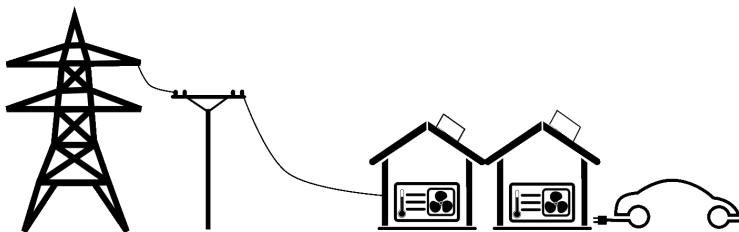
Critical peak power: a problem for DSOs.



When demand exceeds subscribed power.



Critical peak power: exacerbated by EVs.



A plethora of “smart” devices.

Sustainable
innovation

Smart home is happening quickly



15-10-15

Kjell & Company

Sortiment Tillbehör till Kunskapsbank Butiker

Du är här: Hem > Sortiment > El > Elprodukter > Strömkablar

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Be

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- Temperatur
- Luftfuktighet
- Art.nr: 10433



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20/3 - 26/3



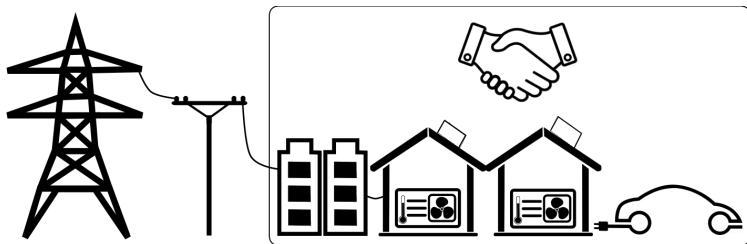
NYA
PRODUKTER
VARJE VECKA

GÖR DITT HEM LITE SMARTARE
Vårkampanj på nätet

Under vår smarta hem-vecka hittar du till & lampor, strömsladdar, sensorer, styrinrättelser, routrar och övervakningskameror till nedsatta priser. Vårkampanjen sträcker sig till och med 24 där vi uppdaterar med nya produkter varje vecka!

N NGENIC

VäxEl: creating a smart energy community.



Model Predictive Control: peak into the future.

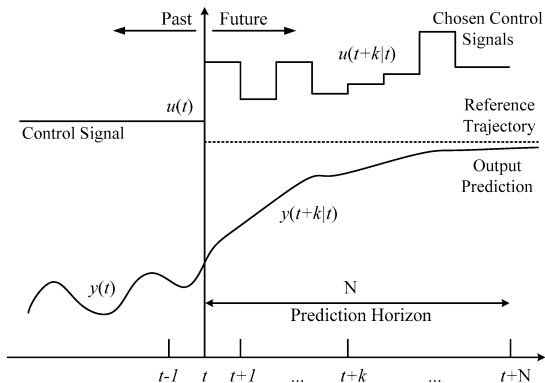


Figure 1: The idea behind model predictive control ¹.

¹Godina, Radu et. al. (2018), *Model Predictive Control Home Energy Management and Optimization Strategy with Demand Response*, Applied Sciences, 8, 3.

Model Predictive Control: optimize over a time horizon.

$$\underset{u}{\text{minimize}} \quad f(x, x^r, u), \quad t \in \Omega \quad (1a)$$

$$\text{subject to} \quad x_{t+1} = Ax_t + Bu_t + Dw_t, \quad t \in \Omega, \quad (1b)$$

$$C^x x_t \leq c_t^x, \quad t \in \Omega, \quad (1c)$$

$$C^u u_t \leq c_t^u, \quad t \in \Omega, \quad (1d)$$

$$C^f x_N \leq c_f^x, \quad (1e)$$

where

- x_t , x_t^r , u_t , and w_t are multivariate time series;
- A , B , and D describe the behavior of the system;
- C^x and c_t^x , C^u and c_t^u , and C^f and c_f^x denote optimization constraints.

Model Predictive Control.

Data: $A, B, D, C^x, c_t^x, C^u, c_t^u, C^f$, and c_f^x

Result: u_{t+1}

repeat

 measure x_t ;

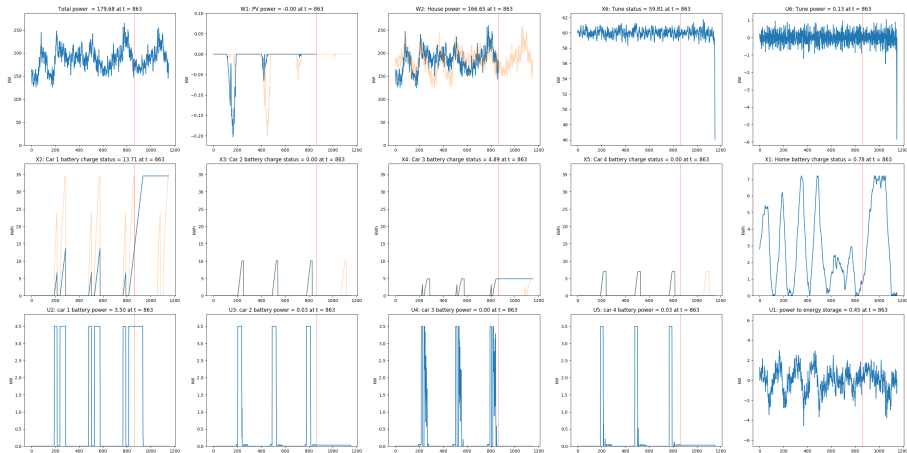
 solve finite-horizon MPC problem to get $u_{t+1}, t+2, \dots, t+N$;

 apply u_{t+1}

$t \leftarrow t + 1$;

Algorithm 1: The basic idea.

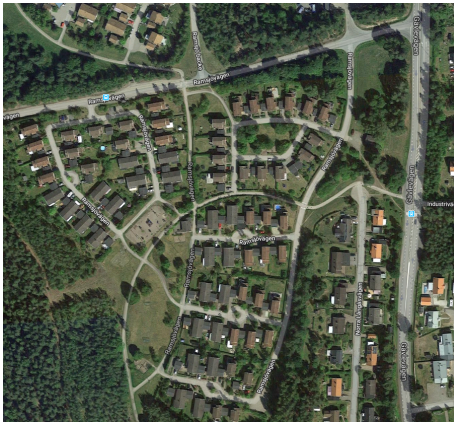
Model Predictive Control: a simulation.



Uppland, Sweden.



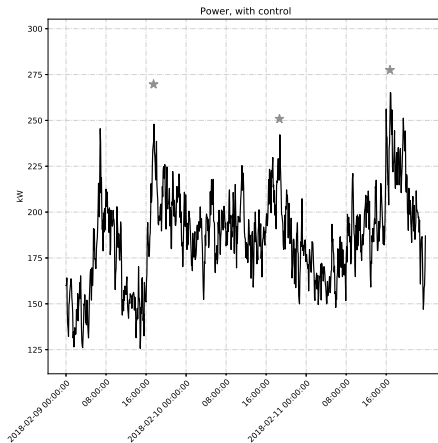
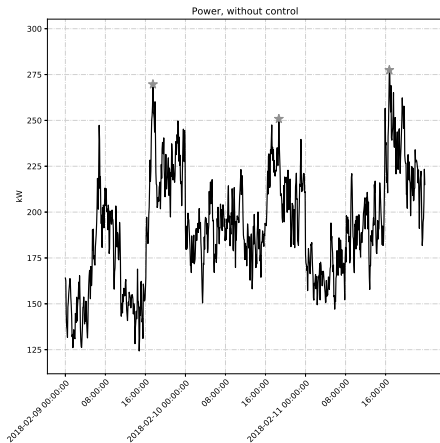
Ramsjöåsen, Björklinge, Uppland.



Scenario.

- a residential area comprised of 60 households;
- 30 households are connected to *Ngenic Tune*;
- the area is serviced by a solar array with a 37 kW production capacity;
- the area is equipped with a FerroAmp *Energy Storage Module* of type $Li(FePO_4)$ with a charge/discharge capacity of 6 kW and a storage capacity of 7.2 kWh;
- 4 households are outfitted with chargestorm *Wallbox EVA Connected* with a charging capacity of 3.7 kW;
- 4 householders drive EVs with different charge profiles.

Results: critical peak power reduced!

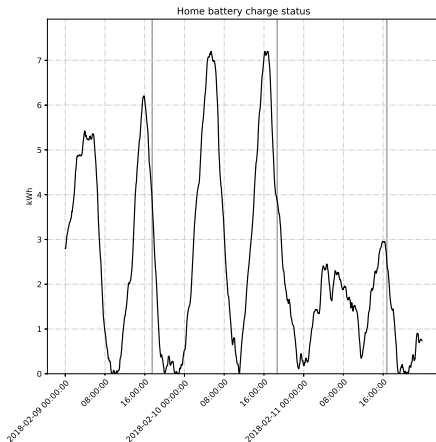


Results: tabulated over three days.

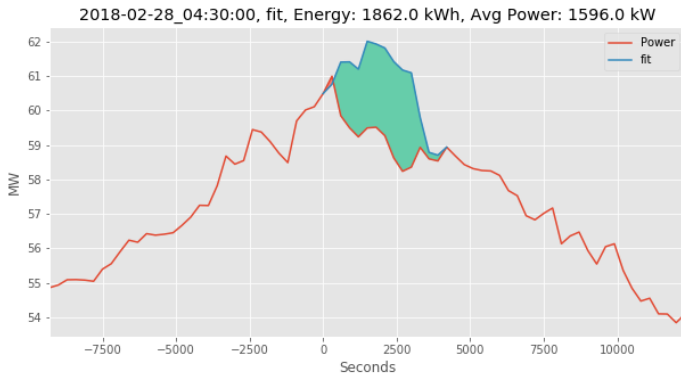
Table 1: Critical peak power values for 60 households.

time stamp	CPP (<i>kW</i>)	optimized (<i>kW</i>)	reduction (<i>kW</i>)
2018-02-09 17:30:00	269.68	238.26	31.42
2018-02-10 18:40:00	250.82	225.05	25.78
2018-02-11 16:45:00	277.46	252.37	25.09
average	265.99	238.55	27.43

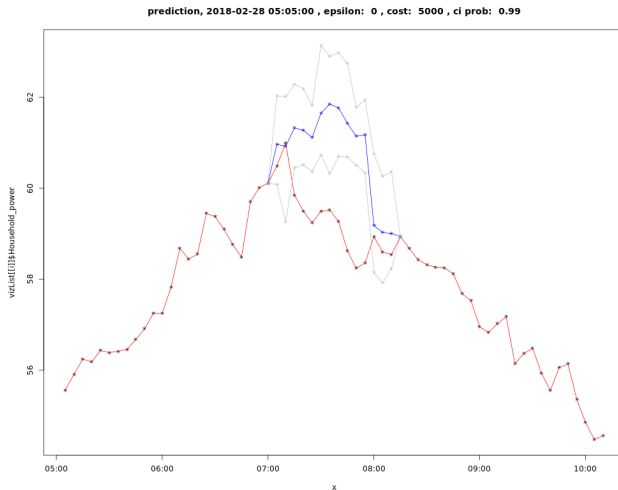
Results: Home battery performance.



Results: coordinating heat-pumps during Feb 2018.



Results, with bootstrapped confidence intervals.



Thanks for your attention!

